

Geometric distance-regular graphs without 4-claws

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Abstract

A non-complete distance-regular graph Γ is called geometric if there exists a set \mathcal{C} of Delsarte cliques such that each edge of Γ lies in a unique clique in \mathcal{C} . In this paper, we determine the non-complete distance-regular graphs satisfying $\max\{3, \frac{8}{3}(a_1 + 1)\} < k < 4a_1 + 10 - 6c_2$. To prove this result, we first show by considering non-existence of 4-claws that any non-complete distance-regular graph satisfying $\max\{3, \frac{8}{3}(a_1 + 1)\} < k < 4a_1 + 10 - 6c_2$ is a geometric distance-regular graph with smallest eigenvalue -3 . Moreover, we classify the geometric distance-regular graphs with smallest eigenvalue -3 . As an application, 7 feasible intersection arrays in the list of [7, Chapter 14] are ruled out.

1 Introduction

Let Γ be a distance-regular graph with valency k and let $\theta_{\min} = \theta_{\min}(\Gamma)$ be its smallest eigenvalue. Any clique C in Γ satisfies

$$|C| \leq 1 - \frac{k}{\theta_{\min}} \quad (1)$$

(see [7, Proposition 4.4.6 (i)]). This bound (1) is due to Delsarte, and a clique C in Γ is called a *Delsarte clique* if C contains exactly $1 - \frac{k}{\theta_{\min}}$ vertices. Godsil [11] introduced the following notion of a geometric distance-regular graph. A non-complete distance-regular graph Γ is called *geometric* if there exists a set \mathcal{C} of Delsarte cliques such that each edge of Γ lies in a unique Delsarte clique in \mathcal{C} . In this case, we say that Γ is geometric with respect to \mathcal{C} .

There are many examples of geometric distance-regular graphs such as bipartite distance-regular graphs, the Hamming graphs, the Johnson graphs, the Grassmann graphs and regular near $2D$ -gons.

In particular, the local structure of geometric distance-regular graphs play an important role in the study of spectral characterization of some distance-regular graphs. In [1], we show that for given

integer $D \geq 2$, any graph cospectral with the Hamming graph $H(D, q)$ is locally the disjoint union of D copies of the complete graph of size $q - 1$, for q large enough. By using this result and [4], we show in [1] that the Hamming graph $H(3, q)$ with $q \geq 36$ is uniquely determined by its spectrum.

Neumaier [17] showed that except for a finite number of graphs, any geometric strongly regular graph with a given smallest eigenvalue $-m$, $m > 1$ integral, is either a Latin square graph or a Steiner graph (see [17] and Remark 4.4 for the definitions).

An n -*claw* is an induced subgraph on $n + 1$ vertices which consists of one vertex of valency n and n vertices of valency 1. Each distance-regular graph without 2-claws is a complete graph. Note that for any geometric distance-regular graph Γ with respect to \mathcal{C} a set of Delsarte cliques, the number of Delsarte cliques in \mathcal{C} containing a fixed vertex is $-\theta_{\min}(\Gamma)$. Hence any geometric distance-regular graph with smallest eigenvalue -2 contains no 3-claws. Blokhuis and Brouwer [6] determined the distance-regular graphs without 3-claws.

Yamazaki [20] considered distance-regular graphs which are locally a disjoint union of three cliques of size $a_1 + 1$, and these graphs for $a_1 \geq 1$ are geometric distance-regular graphs with smallest eigenvalue -3 .

In Theorem 4.3, we determine the geometric distance-regular graphs with smallest eigenvalue -3 . We now state our main result of this paper.

Theorem 1.1 *Let Γ be a non-complete distance-regular graph. If Γ satisfies*

$$\max\{3, \frac{8}{3}(a_1 + 1)\} < k < 4a_1 + 10 - 6c_2$$

then Γ is one of the following.

- (i) *A Steiner graph $S_3(\alpha - 3)$, i.e., a geometric strongly regular graph with parameters $(\frac{(2\alpha - 3)(\alpha - 2)}{3}, 3\alpha - 9, \alpha, 9)$, where $\alpha \geq 36$ and $\alpha \equiv 0, 2 \pmod{3}$.*
- (ii) *A Latin square graph $LS_3(\alpha)$, i.e., a geometric strongly regular graph with parameters $(\alpha^2, 3(\alpha - 1), \alpha, 6)$, where $\alpha \geq 24$.*
- (iii) *The generalized hexagon of order $(8, 2)$ with $\iota(\Gamma) = \{24, 16, 16; 1, 1, 3\}$.*
- (iv) *One of the two generalized hexagons of order $(2, 2)$ with $\iota(\Gamma) = \{6, 4, 4; 1, 1, 3\}$.*
- (v) *A generalized octagon of order $(4, 2)$ with $\iota(\Gamma) = \{12, 8, 8, 8; 1, 1, 1, 3\}$.*
- (vi) *The Johnson graph $J(\alpha, 3)$, where $\alpha \geq 20$.*
- (vii) *$D = 3$ and $\iota(\Gamma) = \{3\alpha + 3, 2\alpha + 2, \alpha + 2 - \beta; 1, 2, 3\beta\}$, where $\alpha \geq 6$ and $\alpha \geq \beta \geq 1$.*
- (viii) *The halved Foster graph with $\iota(\Gamma) = \{6, 4, 2, 1; 1, 1, 4, 6\}$.*
- (ix) *$D = h + 2 \geq 4$ and*

$$(c_i, a_i, b_i) = \begin{cases} (1, \alpha, 2\alpha + 2) & \text{for } 1 \leq i \leq h \\ (2, 2\alpha + \beta - 1, \alpha - \beta + 2) & \text{for } i = h + 1 \\ (3\beta, 3\alpha - 3\beta + 3, 0) & \text{for } i = h + 2 \end{cases}, \text{ where } \alpha \geq \beta \geq 2.$$

(x) $D = h + 2 \geq 3$ and

$$(c_i, a_i, b_i) = \begin{cases} (1, \alpha, 2\alpha + 2) & \text{for } 1 \leq i \leq h \\ (1, \alpha + 2\beta - 2, 2\alpha - 2\beta + 4) & \text{for } i = h + 1 \\ (3\beta, 3\alpha - 3\beta + 3, 0) & \text{for } i = h + 2 \end{cases}, \text{ where } \alpha \geq \beta \geq 2.$$

(xi) A distance-2 graph of a distance-biregular graph with vertices of valency 3 and

$$(c_i, a_i, b_i) = \begin{cases} (1, \alpha, 2\alpha + 2) & \text{for } 1 \leq i \leq h \\ (1, \alpha + 2, 2\alpha) & \text{for } i = h + 1 \\ (4, 2\alpha - 1, \alpha) & \text{for } h + 2 \leq i \leq D - 2 \\ (4, 2\alpha + \beta - 3, \alpha - \beta + 2) & \text{for } i = D - 1 \\ (3\beta, 3\alpha - 3\beta + 3, 0) & \text{for } i = D \end{cases}, \text{ where } \alpha \geq \beta \text{ and } \beta \in \{2, 3\}.$$

Examples of non-complete distance-regular graphs with valency $k > \max\{3, \frac{8}{3}(a_1 + 1)\}$ include Johnson graphs $J(n, e)$ ($(n \geq 20$ and $e = 3)$, $(n \geq 11$ and $e = 4)$ or $(n \geq 2e$ and $e \geq 5)$), Hamming graphs $H(d, q)$ ($(d = 3$ and $q \geq 3)$ or $(d \geq 4$ and $q \geq 2)$) and Grassmann graphs $\begin{bmatrix} V \\ e \end{bmatrix}$ ($(e = 2$ and $q \geq 4)$ or $(e \geq 3$ and $q \geq 2)$), where $n \geq 2e$ and V is an n -dimensional vector space over \mathbb{F}_q the finite field of $q(\geq 2)$ elements (see [7, Chapter 9] for more information on these examples). Except $J(n, 3)$ ($n \geq 20$) and $H(3, q)$ ($q \geq 3$), all the above examples contain 4-claws. Whereas, $J(n, 3)$ ($n \geq 20$) and $H(3, q)$ ($q \geq 3$) are geometric distance-regular graphs with smallest eigenvalue -3 .

In Section 3, we prove Theorem 3.1 which gives a sufficient condition, $\max\{3, \frac{8}{3}(a_1 + 1)\} < k < 4a_1 + 10 - 6c_2$, for geometric distance-regular graphs with smallest eigenvalue -3 . We first show in Theorem 3.2 that for any distance-regular graph satisfying $k > \max\{3, \frac{8}{3}(a_1 + 1)\}$, the statement that Γ has no 4-claws is equivalent to the statement that Γ is geometric with smallest eigenvalue -3 . By using Theorem 3.2, we will prove Theorem 3.1. As an application of Theorem 3.2, we can show non-existence of a family of distance-regular graphs with feasible intersection arrays. For example, in the list of [7, Chapter 14], the 7 feasible intersection arrays in Theorem 3.5 are ruled out.

In Section 4, we determine the geometric distance-regular graphs with smallest eigenvalue -3 in Theorem 4.3. By using Theorem 3.1 and Theorem 4.3, we will prove Theorem 1.1.

2 Preliminaries

All graphs considered in this paper are finite, undirected and simple (for unexplained terminology and more details, see [7]).

For a connected graph Γ , distance $d_\Gamma(x, y)$ between any two vertices x, y in the vertex set $V(\Gamma)$ of Γ is the length of a shortest path between x and y in Γ , and denote by $D(\Gamma)$ the diameter of Γ (i.e., the maximum distance between any two vertices of Γ). For any vertex $x \in V(\Gamma)$, let $\Gamma_i(x)$ be the

set of vertices in Γ at distance precisely i from x , where i is a non-negative integer not exceeding $D(\Gamma)$. In addition, define $\Gamma_{-1}(x) = \Gamma_{D(\Gamma)+1}(x) := \emptyset$ and $\Gamma_0(x) := \{x\}$. For any distinct vertices $x_1, x_2, \dots, x_j \in V(\Gamma)$, define

$$\Gamma_1(x_1, \dots, x_j) := \Gamma_1(x_1) \cap \Gamma_1(x_2) \cap \dots \cap \Gamma_1(x_j).$$

A *clique* is a set of pairwise adjacent vertices. A graph Γ is called *locally G* if any local graph of Γ (i.e., the local graph of a vertex x is the induced subgraph on $\Gamma_1(x)$) is isomorphic to G , where G is a graph. The *adjacency matrix* $A(\Gamma)$ of a graph Γ is the $|V(\Gamma)| \times |V(\Gamma)|$ -matrix with rows and columns are indexed by $V(\Gamma)$, and the (x, y) -entry of $A(\Gamma)$ equals 1 whenever $d_\Gamma(x, y) = 1$ and 0 otherwise. The eigenvalues of Γ are the eigenvalues of $A(\Gamma)$.

A connected graph Γ is called a *distance-regular graph* if there exist integers $b_i(\Gamma)$, $c_i(\Gamma)$, $i = 0, 1, \dots, D(\Gamma)$, such that for any two vertices x, y at distance $i = d_\Gamma(x, y)$, there are precisely $c_i(\Gamma)$ neighbors of y in $\Gamma_{i-1}(x)$ and $b_i(\Gamma)$ neighbors of y in $\Gamma_{i+1}(x)$. In particular, Γ is regular with valency $k(\Gamma) := b_0(\Gamma)$. The numbers $c_i(\Gamma)$, $b_i(\Gamma)$ and $a_i(\Gamma) := k(\Gamma) - b_i(\Gamma) - c_i(\Gamma)$ ($0 \leq i \leq D(\Gamma)$) (i.e., the number of neighbors of y in $\Gamma_i(x)$ for $d_\Gamma(x, y) = i$) are called the *intersection numbers* of Γ . Note that $b_{D(\Gamma)}(\Gamma) = c_0(\Gamma) = a_0(\Gamma) := 0$ and $c_1(\Gamma) = 1$. In addition, we define $k_i(\Gamma) := |\Gamma_i(x)|$ for any vertex x and $i = 0, 1, \dots, D(\Gamma)$. The array $\iota(\Gamma) = \{b_0(\Gamma), b_1(\Gamma), \dots, b_{D(\Gamma)-1}(\Gamma); c_1(\Gamma), c_2(\Gamma), \dots, c_{D(\Gamma)}(\Gamma)\}$ is called the *intersection array* of Γ . In addition, we define the number

$$\mathbf{h}(\Gamma) := |\{j \mid (c_j, a_j, b_j) = (c_1, a_1, b_1), 1 \leq j \leq D(\Gamma) - 1\}| \quad (2)$$

which is called the *head* of Γ .

A regular graph Γ on v vertices with valency $k(\Gamma)$ is called a *strongly regular graph* with parameters $(v, k(\Gamma), \lambda(\Gamma), \mu(\Gamma))$ if there are two constants $\lambda(\Gamma) \geq 0$ and $\mu(\Gamma) > 0$ such that for any two distinct vertices x and y , $|\Gamma_1(x, y)|$ equals $\lambda(\Gamma)$ if $d_\Gamma(x, y) = 1$ and $\mu(\Gamma)$ otherwise.

When there are no confusion, we omit \sim_Γ and $\sim(\Gamma)$ in each notation for Γ , such as $d_\Gamma(\cdot, \cdot)$, $D(\Gamma)$, $A(\Gamma)$, $\mathbf{h}(\Gamma)$, $k(\Gamma)$, $c_i(\Gamma)$, $b_i(\Gamma)$, $a_i(\Gamma)$, $k_i(\Gamma)$, $\lambda(\Gamma)$ and $\mu(\Gamma)$.

Suppose that Γ is a distance-regular graph with valency $k \geq 2$ and diameter $D \geq 2$. It is well-known that Γ has exactly $D + 1$ distinct eigenvalues which are the eigenvalues of the following tridiagonal matrix

$$L_1(\Gamma) := \begin{pmatrix} 0 & b_0 & & & & & \\ c_1 & a_1 & b_1 & & & & \\ & c_2 & a_2 & b_2 & & & \\ & & \cdot & \cdot & \cdot & & \\ & & & c_i & a_i & b_i & \\ & & & & \cdot & \cdot & \cdot \\ & & & & & c_{D-1} & a_{D-1} & b_{D-1} \\ & & & & & & c_D & a_D \end{pmatrix} \quad (3)$$

(cf. [7, p.128]). In particular, we denote by $\theta_{\min} = \theta_{\min}(\Gamma)$ the smallest eigenvalue of Γ .

3 Distance-regular graphs without 4-claws

In this section, we prove the following theorem which gives a sufficient condition for geometric distance-regular graphs with smallest eigenvalue -3 .

Theorem 3.1 *Let Γ be a non-complete distance-regular graph. If Γ satisfies*

$$\max\{3, \frac{8}{3}(a_1 + 1)\} < k < 4a_1 + 10 - 6c_2 \quad (4)$$

then Γ is a geometric distance-regular graph with smallest eigenvalue -3 .

We first show in Theorem 3.2 that for any distance-regular graph satisfying $k > \max\{3, \frac{8}{3}(a_1 + 1)\}$, the statement that Γ has no 4-claws is equivalent to the statement that Γ is geometric with smallest eigenvalue -3 . By using Theorem 3.2, we will prove Theorem 3.1. As an application, by considering a restriction on c_2 in Lemma 3.4, we can rule out a family of feasible intersection arrays. In particular, we prove that there are no distance-regular graphs with the intersection arrays in Theorem 3.5.

Theorem 3.2 *Let Γ be a distance-regular graph satisfying $k > \max\{3, \frac{8}{3}(a_1 + 1)\}$. Then the following are equivalent.*

- (i) Γ has no 4-claws.
- (ii) Γ is a geometric distance-regular graph with smallest eigenvalue -3 .

Proof: Let Γ be a distance-regular graph satisfying $k > \max\{3, \frac{8}{3}(a_1 + 1)\}$. Let $\theta_{\min} = \theta_{\min}(\Gamma)$.

(ii) \Rightarrow (i): Suppose that Γ is geometric with respect to \mathcal{C} a set of Delsarte cliques and $\theta_{\min} = -3$. Since the number of Delsarte cliques in \mathcal{C} containing a given vertex is $-\theta_{\min}$, the statement (i) follows immediately.

(i) \Rightarrow (ii): Suppose that Γ has no 4-claws. Define a *line* to be a maximal clique C in Γ such that C has at least $k - 2(a_1 + 1) + 1$ vertices. Note here that $a_1 \geq 1$ follows, otherwise Γ has a 4-claw from $k > \max\{3, \frac{8}{3}(a_1 + 1)\}$. Hence, $|C| \geq 3$ for any line C in Γ . If there exists a line C satisfying $|C| = 3$, then $a_1 = 1$ and $k = 6$ both hold by $3 \geq k - 2(a_1 + 1) + 1$ and $k > \frac{8}{3}(a_1 + 1)$. By [12, Theorem 1.1], the graph Γ is one of the following.

- (a) The generalized quadrangle of order $(2, 2)$.
- (b) One of the two generalized hexagons of order $(2, 2)$.
- (c) The Hamming graph $H(3, 3)$.
- (d) The halved Foster graph.

All the graphs in (a)-(d) are geometric with smallest eigenvalue -3 .

In the rest of the proof, we assume that each line contains more than 3 vertices. First, we prove the following claim.

Claim 3.3 *Every edge of Γ lies in a unique line.*

Proof of Claim 3.3: Let (x, y_1) be an arbitrary edge in Γ . As $k \geq 2(a_1 + 1) + 1$, there exists a 3-claw containing x and y_1 , say $\{x, y_1, y_2, y_3\}$ induces a 3-claw, where $y_i \in \Gamma_1(x)$ ($i = 1, 2, 3$). Put $Y_i := \{y_i\} \cup \Gamma_1(x, y_i)$ ($i = 1, 2, 3$). If there exists a vertex z in $\Gamma_1(x) \setminus \cup_{i=1}^3 Y_i$, then $\{x, z, y_1, y_2, y_3\}$ induces a 4-claw which is impossible, and therefore $\Gamma_1(x) = \cup_{i=1}^3 Y_i$ follows. If there exist non-adjacent two vertices v, w in $Y_1 \setminus (Y_2 \cup Y_3)$, then the set $\{x, y_2, y_3, v, w\}$ induces a 4-claw which is a contradiction. Hence $\{x\} \cup (Y_1 \setminus (Y_2 \cup Y_3))$ induces a clique containing the edge (x, y_1) , and it satisfies

$$|\{x\} \cup (Y_1 \setminus (Y_2 \cup Y_3))| = |\{x\}| + |\Gamma_1(x)| - |Y_2 \cup Y_3| \geq 1 + k - 2(a_1 + 1).$$

Thus every edge lies in a line.

Assume that there exist two lines C_z and C_w containing the edge (x, y_1) , where $z \in C_z$ and $w \in C_w$ are two non-adjacent vertices. Then $a_1 = |\Gamma_1(x, y_1)| \geq 2(k - 2(a_1 + 1) - 1) - (|C_z \cap C_w| - 2)$ implies

$$|C_z \cap C_w| \geq 2k - 5a_1 - 4. \quad (5)$$

In addition, by (5),

$$\begin{aligned} |\Gamma_1(x) \setminus (\Gamma_1(x, z) \cup \Gamma_1(x, w) \cup \{z, w\})| &\geq k - (|\Gamma_1(x, z)| + |\Gamma_1(x, w)| + |\{z, w\}| - (|C_z \cap C_w| - 1)) \\ &\geq k - (2(a_1 + 1) - (2k - 5a_1 - 5)) \\ &= 3k - 7a_1 - 7. \end{aligned} \quad (6)$$

Since Γ has no 4-claws, $(\{x\} \cup \Gamma_1(x)) \setminus (\Gamma_1(x, z) \cup \Gamma_1(x, w) \cup \{z, w\})$ induces a clique of size at least $3k - 7a_1 - 6$ by (6). Since any clique in Γ has size at most $a_1 + 2$, we have $k \leq \frac{8}{3}(a_1 + 1)$ which is impossible. Hence, the edge (x, y_1) lies in a unique line. Now, Claim 3.3 is proved. ■

For each vertex $x \in V(\Gamma)$, we define M_x to be the number of lines containing x . Then for any vertex x , we have $M_x \geq 3$ as $k > \frac{8}{3}(a_1 + 1) > 2(a_1 + 1)$, and hence

$$M_x = 3 \text{ for each vertex } x \in V(\Gamma) \quad (7)$$

as $k \geq M_x(k - 2(a_1 + 1))$ holds by Claim 3.3. Let B be the vertex-line incidence matrix (i.e., the $(0, 1)$ -matrix with rows and columns are indexed by the vertex set and the set of lines of Γ respectively, where (x, C) -entry of B is 1 if the vertex x is contained in the line C and 0 otherwise). By Claim 3.3 and (7), $BB^T = A + 3I$ holds, where B^T is the transpose of B , $A = A(\Gamma)$ and I is the $|V(\Gamma)| \times |V(\Gamma)|$ identity matrix. Since each line contains more than 3 vertices, it follows by double-counting the number of ones in B that the number of lines is strictly less than the number of vertices in Γ . Hence, the matrix BB^T is singular so that 0 is an eigenvalue of BB^T and thus -3 is an eigenvalue of A . As BB^T is positive semidefinite, we find $\theta_{\min} = -3$. Hence it follows by (1), Claim 3.3, (7) and $\theta_{\min} = -3$ that every line has exactly $1 + \frac{k}{3}$ vertices. This proves that Γ is geometric with $\theta_{\min} = -3$. ■

In [16, Lemma 2], Koolen and Park have shown the following lemma.

Lemma 3.4 *Let Γ be a distance-regular graph with a 4-claw. Then Γ satisfies*

$$c_2 \geq \frac{4a_1 + 10 - k}{6}.$$

Proof: Suppose that $\{x, y_i \mid 1 \leq i \leq 4\}$ induces a 4-claw in Γ , where $y_i \in \Gamma_1(x)$ ($i = 1, 2, 3, 4$). It follows by the principle of inclusion and exclusion that

$$\begin{aligned} k &\geq |\{y_i \mid 1 \leq i \leq 4\}| + |\cup_{i=1}^4 \Gamma_1(x, y_i)| \\ &\geq |\{y_i \mid 1 \leq i \leq 4\}| + \sum_{i=1}^4 |\Gamma_1(x, y_i)| - \sum_{1 \leq i < j \leq 4} |\Gamma_1(x, y_i, y_j)| \\ &\geq 4 + 4a_1 - \binom{4}{2}(c_2 - 1), \end{aligned}$$

from which Lemma 3.4 follows. ■

We now prove our main result of Section 3, Theorem 3.1.

Proof of Theorem 3.1: Suppose that Γ is a non-complete distance-regular graph satisfying (4). Then there are no 4-claws in Γ by Lemma 3.4, so that Γ is geometric with $\theta_{\min}(\Gamma) = -3$ by Theorem 3.2. This completes the proof. ■

Theorem 3.5 *There are no distance-regular graphs with the following intersection arrays*

- (i) $\{55, 36, 11; 1, 4, 45\}$,
- (ii) $\{56, 36, 9; 1, 3, 48\}$,
- (iii) $\{65, 44, 11; 1, 4, 55\}$,
- (iv) $\{81, 56, 24, 1; 1, 3, 56, 81\}$,
- (v) $\{117, 80, 32, 1; 1, 4, 80, 117\}$,
- (vi) $\{117, 80, 30, 1; 1, 6, 80, 117\}$,
- (vii) $\{189, 128, 45, 1; 1, 9, 128, 189\}$.

Proof: Assume that Γ is a distance-regular graph such that its intersection array is one of the 7 intersection arrays (i)-(vii). Since Γ satisfies $k > \frac{8}{3}(a_1 + 1)$, $a_1 \neq 0$ and $\theta_{\min}(\Gamma) \neq -3$, Γ has a 4-claw by Theorem 3.2. It follows by Lemma 3.4 that $c_2 \geq \frac{4a_1+10-k}{6}$ which is impossible. This shows Theorem 3.5. ■

Remark 3.6 (a) *Koolen and Park [16] showed the non-existence of distance-regular graphs with the intersection array (iii) in Theorem 3.5 and so did Jurišić and Koolen [14] for the intersection arrays (iv)-(vii).*

(b) *Suppose that Γ is a distance-regular graph with an intersection array (i), (ii) or (iii) in Theorem 3.5. By [7, Proposition 4.2.17], Γ_3 (the graph with the vertices are $V(\Gamma)$ and the edges are the 2-subsets of vertices at distance 3 in Γ) is a strongly regular graph with parameters $(672, 121, 20, 22)$, $(855, 126, 21, 18)$ or $(924, 143, 22, 22)$, respectively. No strongly regular graphs with these parameters are known.*

4 Geometric distance-regular graphs with smallest eigenvalue -3

In this section, we prove Theorem 4.3 in which we determine the geometric distance-regular graphs with smallest eigenvalue -3 .

Let Γ be a distance-regular graph with diameter $D = D(\Gamma)$. For any non-empty subset X of $V(\Gamma)$ and for each $i = 0, 1, \dots, D$, we put

$$X_i := \{x \in V(\Gamma) \mid d(x, X) = i\},$$

where $d(x, X) = \min\{d(x, y) \mid y \in X\}$. Suppose that $C \subseteq V(\Gamma)$ is a Delsarte clique in Γ . For each $i = 0, 1, \dots, D-1$ and for a vertex $x \in C_i$, define

$$\psi_i(x, C) := |\{z \in C \mid d(x, z) = i\}|.$$

The number $\psi_i(x, C)$ ($i = 0, 1, \dots, D-1$) depends not on the pair (x, C) but depends only on the distance $i = d(x, C)$ (cf. [2, Section 4] and [10, Section 11.7]). Hence denote

$$\psi_i := \psi_i(x, C) \quad (i = 0, 1, \dots, D-1).$$

Now, let Γ be geometric with respect to \mathcal{C} a set of Delsarte cliques. For $x, y \in V(\Gamma)$ with $d(x, y) = i$ ($i = 1, 2, \dots, D$), define $\tau_i(x, y; \mathcal{C})$ as the number of cliques C in \mathcal{C} satisfying $x \in C$ and $d(y, C) = i-1$. By [2, Lemma 4.1], the number $\tau_i(x, y; \mathcal{C})$ ($i = 1, 2, \dots, D$) depends not on the pair (x, y) and \mathcal{C} , but depends only on the distance $i = d(x, y)$. Thus we may put

$$\tau_i := \tau_i(x, y; \mathcal{C}) \quad (i = 1, 2, \dots, D).$$

Note that for any geometric distance-regular graph Γ ,

$$\tau_D = -\theta_{\min} \tag{8}$$

holds, where $D = D(\Gamma)$ and $\theta_{\min} = \theta_{\min}(\Gamma)$.

The next lemma is a direct consequence of [2, Proposition 4.2 (i)].

Lemma 4.1 *Let Γ be a geometric distance-regular graph. Then the following hold.*

- (i) $b_i = -(\theta_{\min} + \tau_i) \left(1 - \frac{k}{\theta_{\min}} - \psi_i\right)$ ($1 \leq i \leq D-1$).
- (ii) $c_i = \tau_i \psi_{i-1}$ ($1 \leq i \leq D$).

Note that by (8) and Lemma 4.1 (ii), any geometric distance-regular graph with diameter D satisfies

$$c_D = (-\theta_{\min})\psi_{D-1} \geq -\theta_{\min}. \tag{9}$$

Lemma 4.2 *Let Γ be a geometric distance-regular graph. Then*

$$\psi_1 \leq \tau_2 \leq -\theta_{\min}. \tag{10}$$

In particular, $\psi_1^2 \leq c_2 \leq \theta_{\min}^2$ holds.

Proof: Let x be a vertex and let C be a Delsarte clique satisfying $x \notin C$. If there are two neighbors y and z of x in C , then two edges (x, y) and (x, z) lie in different Delsarte cliques as Γ is geometric. This shows $\psi_1 \leq \tau_2$. Note that the number of Delsarte cliques containing any fixed vertex is $-\theta_{\min}$, so that $\tau_i \leq -\theta_{\min}$ for all $i = 1, \dots, D$. Hence, we find $\psi_1 \leq \tau_2 \leq -\theta_{\min}$. In particular, it follows by Lemma 4.1 (ii) and (10) that $\psi_1^2 \leq \tau_2 \psi_1 = c_2 \leq \theta_{\min}^2$ holds. ■

Theorem 4.3 *Let Γ be a geometric distance-regular graph with smallest eigenvalue -3 . Then Γ satisfies one of the following.*

- (i) $k = 3$ and Γ is one of the following graphs: the Heawood graph, the Pappus graph, Tutte's 8-cage, the Desargues graph, Tutte's 12-cage, the Foster graph, $K_{3,3}$, $H(3, 2)$.
- (ii) A Steiner graph $S_3(\alpha-3)$, i.e., a geometric strongly regular graph with parameters $\left(\frac{(2\alpha-3)(\alpha-2)}{3}, 3\alpha-9, \alpha, 9\right)$, where $\alpha \geq 6$ and $\alpha \equiv 0, 2 \pmod{3}$.
- (iii) A Latin square graph $LS_3(\alpha)$, i.e., a geometric strongly regular graph with parameters $(\alpha^2, 3(\alpha-1), \alpha, 6)$, where $\alpha \geq 4$.
- (iv) The generalized $2D$ -gon of order $(s, 2)$, where $(D, s) = (2, 2), (2, 4), (3, 8)$.
- (v) One of the two generalized hexagons of order $(2, 2)$ with $\iota(\Gamma) = \{6, 4, 4; 1, 1, 3\}$.
- (vi) A generalized octagon of order $(4, 2)$ with $\iota(\Gamma) = \{12, 8, 8, 8; 1, 1, 1, 3\}$.
- (vii) The Johnson graph $J(\alpha, 3)$, where $\alpha \geq 6$.
- (viii) $D = 3$ and $\iota(\Gamma) = \{3\alpha+3, 2\alpha+2, \alpha+2-\beta; 1, 2, 3\beta\}$, where $\alpha \geq \beta \geq 1$.
- (ix) The halved Foster graph with $\iota(\Gamma) = \{6, 4, 2, 1; 1, 1, 4, 6\}$.
- (x) $D = h+2 \geq 4$ and

$$(c_i, a_i, b_i) = \begin{cases} (1, \alpha, 2\alpha+2) & \text{for } 1 \leq i \leq h \\ (2, 2\alpha+\beta-1, \alpha-\beta+2) & \text{for } i = h+1 \\ (3\beta, 3\alpha-3\beta+3, 0) & \text{for } i = h+2 \end{cases}, \text{ where } \alpha \geq \beta \geq 2.$$

- (xi) $D = h+2 \geq 3$ and

$$(c_i, a_i, b_i) = \begin{cases} (1, \alpha, 2\alpha+2) & \text{for } 1 \leq i \leq h \\ (1, \alpha+2\beta-2, 2\alpha-2\beta+4) & \text{for } i = h+1 \\ (3\beta, 3\alpha-3\beta+3, 0) & \text{for } i = h+2 \end{cases}, \text{ where } \alpha \geq \beta \geq 2.$$

- (xii) A distance-2 graph of a distance-biregular graph with vertices of valency 3 and

$$(c_i, a_i, b_i) = \begin{cases} (1, \alpha, 2\alpha+2) & \text{for } 1 \leq i \leq h \\ (1, \alpha+2, 2\alpha) & \text{for } i = h+1 \\ (4, 2\alpha-1, \alpha) & \text{for } h+2 \leq i \leq D-2 \\ (4, 2\alpha+\beta-3, \alpha-\beta+2) & \text{for } i = D-1 \\ (3\beta, 3\alpha-3\beta+3, 0) & \text{for } i = D \end{cases}, \text{ where } \alpha \geq \beta \text{ and } \beta \in \{2, 3\}.$$

Proof: Let Γ be geometric with respect to \mathcal{C} . As $\theta_{\min} = -3$, we have $k \equiv 0 \pmod{3}$. If $k = 3$ then Γ satisfies (i) by [5] (cf.[7, Theorem 7.5.1]). In the rest of the proof, we assume $k \geq 6$ and let $D = D(\Gamma)$. We divide the proof into two cases, (**Case 1:** $c_2 \geq 2$) and (**Case 2:** $c_2 = 1$).

Case 1: $c_2 \geq 2$

By (10) with $\theta_{\min} = -3$, we find $\psi_1 \in \{1, 2, 3\}$.

First suppose $\psi_1 = 1$, so that Γ is locally a disjoint union of three cliques of size $a_1 + 1$ and $k = 3(a_1 + 1)$. By [20, Theorem 3.1], Γ satisfies either $(c_2 = 2 \text{ and } 2 \leq D \leq 3)$ or $(c_2 = 3 \text{ and } D = 2)$. If $c_2 = 2$ and $D = 2$ then -3 is not the smallest eigenvalue of the matrix $L_1(\Gamma)$ in (3), which contradicts to $\theta_{\min} = -3$. If $c_2 = 2$ and $D = 3$ then $\tau_2 = 2$ and $\tau_3 = 3$ by Lemma 4.1 (ii) and (8), respectively, and thus $(c_1, a_1, b_1) = (1, a_1, 2a_1 + 2)$, $(c_2, a_2, b_2) = (2, 2a_1 - 1 + \psi_2, a_1 + 2 - \psi_2)$ and $(c_3, a_3, 0) = (3\psi_2, 3a_1 + 3 - 3\psi_2, 0)$ all hold by Lemma 4.1. Now, Γ satisfies (viii). If $c_2 = 3$ and $D = 2$, then Γ is the generalized quadrangle of order $(s, 2)$, where $s = 2, 4$ (cf. [7, Theorem 6.5.1] and [13, Theorem 1]).

Next suppose $\psi_1 = 2$, so that $\tau_2 \in \{2, 3\}$, $b_1 = \frac{2(k-3)}{3}$ and $c_2 = 2\tau_2$ all follow by (10) and Lemma 4.1. If $D \geq 3$ then Γ is the Johnson graph $J(\alpha, 3)$ ($\alpha \geq 6$) of diameter 3 by [15, Theorem 7.1] and [3, Remark 2 (ii)]. Now, we consider $D = 2$. Then, $\tau_2 = 3$ by (8), and Γ is a strongly regular graph with parameters $(a_1^2, 3(a_1 - 1), a_1, 6)$, where $a_1 \geq 4$ as $k \geq 6$ and Γ is geometric. Hence, (iii) follows as Γ is the line graph of a $2 - (3\alpha, 3, 1)$ -transversal design, where \mathcal{C} and $V(\Gamma)$ are the set of points and lines respectively (See Remark 4.4 (b)).

Finally, we consider $\psi_1 = 3$. Then $c_2 = \tau_2\psi_1 = 9$ holds by Lemma 4.2. From Lemma 4.1 (i) with $\theta_{\min} + \tau_2 = 0$, $D = 2$ follows, and thus $(c_1, a_1, b_1) = (1, a_1, 2a_1 - 10)$ and $(c_2, a_2, b_2) = (9, 3a_1 - 18, 0)$. Since Γ is geometric, Γ is a Steiner graph $S_3(\alpha - 3)$ and Γ satisfies (ii), where the restriction on a_1 is obtained from $k \geq 6$ and the fact that $|V(\Gamma)|$ is a positive integer (See [17, p.396] and Remark 4.4). This completes the proof of **Case 1**.

Case 2: $c_2 = 1$

From the conditions $c_2 = \tau_2\psi_1 = 1$ and $\theta_{\min} = -3$, Γ is locally a disjoint union of three cliques of size $a_1 + 1$. If $a_1 \leq 1$ then $k \in \{3, 6\}$ follows from $|C| \in \{2, 3\}$ for any Delsarte clique C in Γ . By [12], Γ satisfies (v) or (ix).

From now on, we assume $a_1 \geq 2$. First suppose $c_{\mathbf{h}+1} \geq 2$, where $\mathbf{h} = \mathbf{h}(\Gamma)$ is the head of Γ in (2). Then by (9) and [20, Theorem 3.1], Γ satisfies either $(c_{\mathbf{h}+1} = 3 \text{ and } D = \mathbf{h} + 1)$ or $(c_{\mathbf{h}+1} = 2 \text{ and } D = \mathbf{h} + 2)$. For the case $c_{\mathbf{h}+1} = 3$, Γ is a generalized $2D$ -gon of order $(s, 2)$, where $(D, s) = (3, 8), (4, 4)$ (cf. [7, Section 6.5] and [13, Theorem 1]). If $c_{\mathbf{h}+1} = 2$, then we find $\psi_{\mathbf{h}} = 1$ and $\tau_{\mathbf{h}+1} = 2$ by $c_{\mathbf{h}} = \psi_{\mathbf{h}-1}\tau_{\mathbf{h}} = 1$ and

$$a_1 = a_{\mathbf{h}} = \tau_{\mathbf{h}}(a_1 + 1 - \psi_{\mathbf{h}-1}) + (3 - \tau_{\mathbf{h}})(\psi_{\mathbf{h}} - 1),$$

from which (x) holds by (8), Lemma 4.1 and [13, Proposition 2]. Next suppose $c_{\mathbf{h}+1} = 1$. By (9) and [20, Theorem 4.1], Γ satisfies either $D = \mathbf{h} + 2$ or (xii). For the case $D = \mathbf{h} + 2$ with $c_{\mathbf{h}+1} = 1$, (xi) follows by (8) and Lemma 4.1. This completes the proof of Theorem 4.3. ■

We remark on the distance-regular graphs in Theorem 4.3.

- Remark 4.4** (a) The line graph of a Steiner triple system on $2\alpha - 3$ points for any integer $\alpha \geq 6$ satisfying $\alpha \equiv 0, 2 \pmod{3}$, which is called a Steiner graph $S_3(\alpha - 3)$, is a strongly regular graph given in (ii). With the fact that a Steiner triple system on v points exists for each integer v satisfying $v \equiv 1$ or $3 \pmod{6}$, Wilson showed in [18] and [19] that there are super-exponentially many Steiner triple systems for an admissible number of points, hence so are strongly regular graphs in (ii) (cf. [8, p. 209], [17, Lemma 4.1]).
- (b) The line graph of a $2 - (mn, m, 1)$ -transversal design ($n \geq m + 1$) is called a Latin square graph $LS_m(n)$ (See [17, p.396]). In particular, a Latin square graph $LS_3(\alpha)$ is a geometric strongly regular graph in (iii). Since there are more than exponentially many Latin squares of order α , so are such strongly regular graphs in (iii) (cf. [8, p. 210], [17, Lemma 4.2]).
- (c) In the list of [7, Chapter 14], only the Hamming graph $H(3, \alpha + 2)$, the Doob graph of diameter 3 and the intersection array $\{45, 30, 7; 1, 2, 27\}$ satisfy (viii). No distance-regular graph with the last array, $\{45, 30, 7; 1, 2, 27\}$, is known. We can also check that if Γ satisfies (viii) then the eigenvalues of Γ are integers.

Proof of Theorem 1.1: It is straightforward from Theorem 3.1 and Theorem 4.3. ■

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